## Lab 5

# **AR Markers**

This lecture is part of the RACECAR-MN introductory robotics course. You can visit the course webpage at <u>mitll-racecar-mn.readthedocs.io</u>.



### **Objectives**

**Main Objective**: Combine your previous lab solutions to complete the time trial racecourse

#### **Learning Objectives**

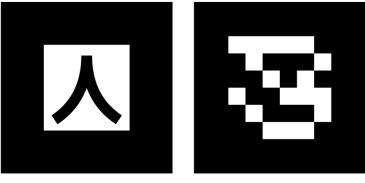
- Identify the location, orientation, and id of AR markers in a color image
- Make decisions based on information provided by AR markers



### **AR Markers**

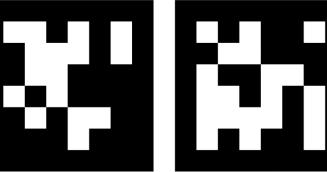
- Fiducial markers used for <u>a</u>ugmented <u>reality</u>
- Common characteristics:
  - high contrast
  - bi-tonal
  - square
  - bordered

#### 1. ARToolKit 2. ARTag



3. AprilTag

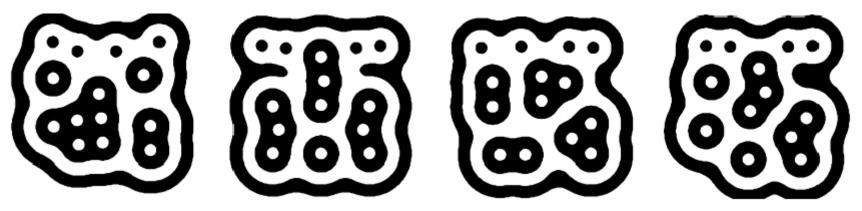






### **AR Markers - Outliers**

#### ReacTIVision



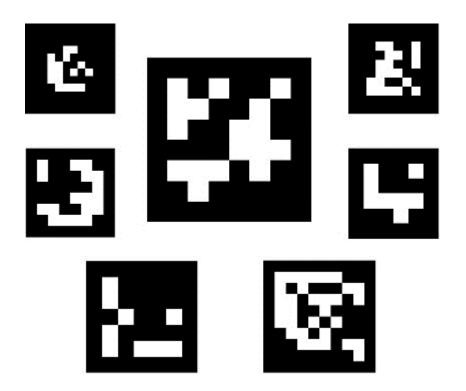
ARToolKit





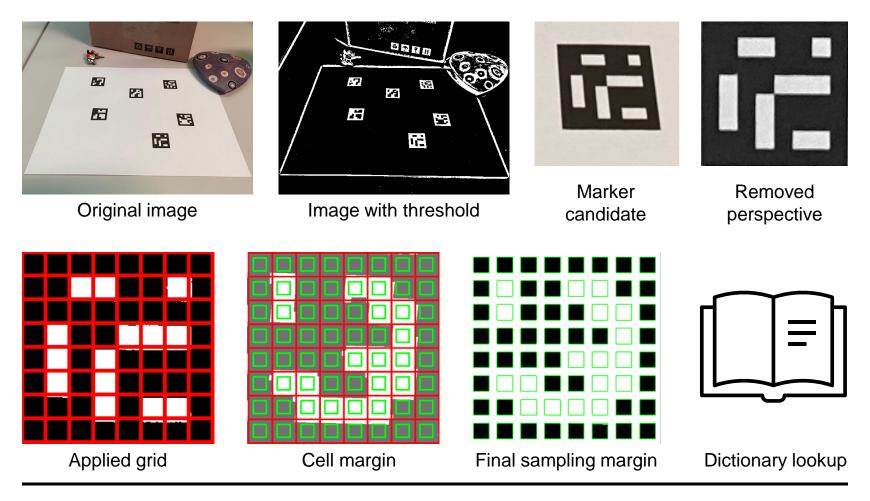
### ArUco OpenCV

- Border of black with a binary encoding in the center
- Checks orientation
- Marker id is not determined by binary coding in the marker but the index in a defined dictionary



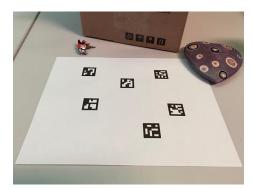


### ArUco OpenCV





### **ArUco OpenCV**



Original image

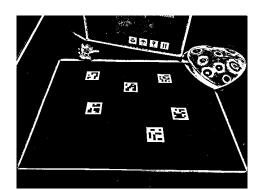
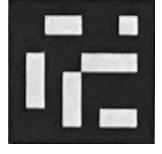


Image with threshold



Marker candidate

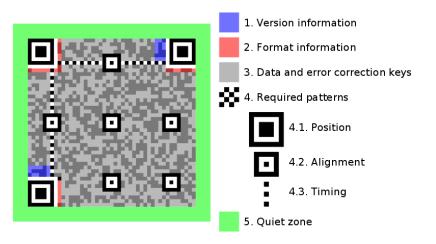


Removed perspective



### **Information Gained**

- ArUco Markers encode
  - Corner location
  - Marker id (dictionary index)
- QR Codes encode
  - Binary data





### QR vs AR



- QR codes have all the common characteristics of AR markers but are commonly used to direct to a URL
- What major differences are there between QR codes and AR markers like ArUco markers?
- Why would a QR code be a bad AR marker?

